

Target Tracking for Contextual Bandits: Application to Demand Side Management

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Introduction

Motivation

As electricity is hard to store, balance between production and demand must be maintained at any time.

Current solution:

Forecast consumption and adapt production accordingly

- ▶ As renewable energies are subject to weather conditions, production becomes harder to adjust
- ▶ New communication tools (smart meters) will provide access to data and instantaneous communication

Prospective solution:

Send incentive signals (electricity tariff variations) to manage demand response

Problem

How to optimize these signals learning from clients behaviors?

Learn from clients behaviors & **Optimize tariffs sending** Exploration - **Exploitation** trade-off

Idea

Apply contextual-bandit theory to demand side management by offering price incentives



Setting and model

Modeling of the electricity consumption

Some exogenous factors (temperature, day, etc.) form, at an instance t , a context vector $x_t \in \mathcal{X}$. The individual consumption of a customer getting the price level $j \in \{1, \dots, K\}$ is $\psi(x_t, j) +$ white noise. A share $p_{t,j}$ of customers receives tariff j at t . The mean consumption observed for an homogeneous population, with $p_t \in \mathcal{P} \subset \{(p_1, \dots, p_K) \in [0, 1]^K \mid \sum_k p_k = 1\}$, equals

$$Y_{t,p_t} = \sum_{j=1}^K p_{t,j} \psi(x_t, j) + \text{noise.}$$

Assumption.

There is an unknown vector θ and a known function ϕ such that $\sum_{j=1}^K p_{t,j} \psi(x_t, j) = \phi(x_t, p_t)^T \theta$.

Model 1. Tariff-dependent noise

$$Y_{t,p_t} = \phi(x_t, p_t)^T \theta + p_t^T \varepsilon_t$$

Sub-Gaussian i.i.d noise vectors $\varepsilon_1, \dots, \varepsilon_t$ with $\mathbb{E}[\varepsilon_1] = (0, \dots, 0)^T$ and $\text{Var}(\varepsilon_1) = \Gamma$

Model 2. Global noise

$$Y_{t,p_t} = \phi(x_t, p_t)^T \theta + e_t$$

Sub-Gaussian i.i.d scalar noises e_1, \dots, e_t with $\mathbb{E}[e_1] = 0$ and $\text{Var}(e_1) = \sigma^2$

Target Tracking for Contextual Bandits

Inputs

Parametric context set \mathcal{X}
Set of legible convex weights \mathcal{P}
Transfer function $\phi: \mathcal{X} \times \mathcal{P} \rightarrow \mathbb{R}^d$
Bound on mean consumptions C

Unknown parameters

Transfer parameter $\theta \in \mathbb{R}^d$
Covariance matrix $\Gamma \in \mathcal{M}_K(\mathbb{R})$ (Model 1)
or Variance σ^2 (Model 2)

- At $t=1, 2, \dots$
- 👁 Observe a context $x_t \in \mathcal{X}$ and a target $c_t \in (0, C)$
 - 👉 Choose an allocation of price levels $p_t \in \mathcal{P}$
 - 👁 Observe a resulting mean consumption $Y_{t,p_t} \in (0, C)$
 - 👎 Suffer a loss $\ell_t = (Y_{t,p_t} - c_t)^2$

Aim. Minimize the cumulative loss

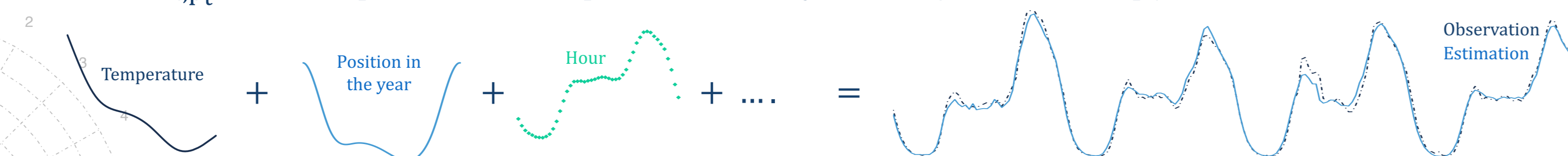
$$L_T = \sum_{t=1}^T (Y_{t,p_t} - c_t)^2$$

Data*

Consumption at half-an-hour intervals of 1 100 clients subjected to Dynamic Time of Use energy prices three tariffs: **Low**, **Normal**, **High**

A generalized additive model for consumption

$$Y_{t,p_t} = f_1(\text{temperature}) + f_2(\text{position in the year}) + f_3(\text{hour}) + f_4(p_t) + \dots + \text{noise}$$



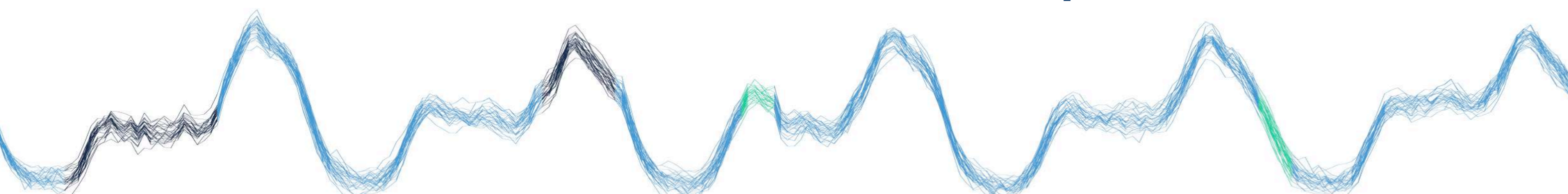
With $(x_i)_i$ explicative variables, $\mathbb{E}[Y] = \sum_i f_i(x_i)$

- ▶ if x_i is a discrete variable with m modalities: $f_i(x_i) = \sum_{j=1}^m \alpha_j \mathbf{1}_{x_i=j}$
- ▶ if x_i is a continuous variable, f_i is a spline: C^2 -function defined piecewise by polynomials

There is a known transfer function ϕ and an unknown parameter θ such that $\mathbb{E}[Y] = \phi(x)^T \theta$

Realistic simulator. Context + Price level \rightarrow Mean consumption

- ▶ Select customers with more than 95% of data available and consider their mean consumption
- ▶ Estimate covariance matrix Γ
- ▶ Build a simulator based on Generalized Additive Model to run the experiments



* Low Carbon London - UK Power Networks - "Smart Meter Energy Consumption Data in London Households"

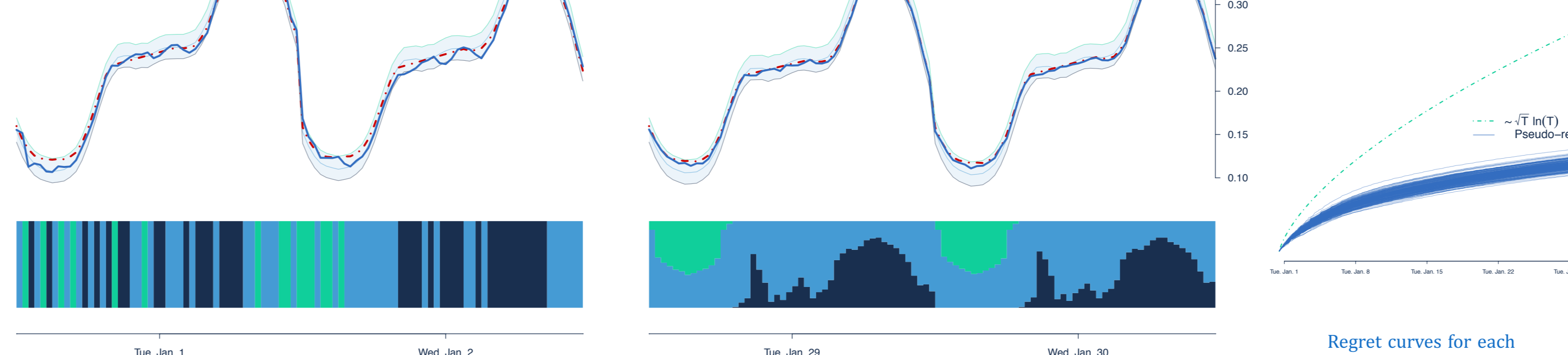
Experiments

\mathcal{P} restriction: only two tariffs at the same round. Population split into 100 equal parts. Target creation: smooth attainable targets.

Training period: a year of data using historical contexts with only Normal tariffs picked.

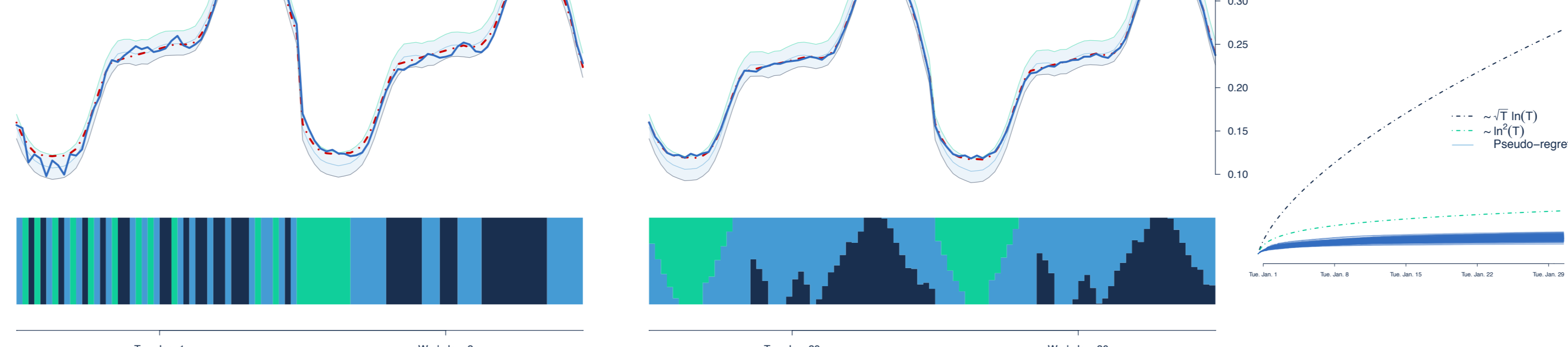
Testing period: a month exploring the effects of tariffs, picking p_t according to the algorithm.

Model 1



Top: average of mean consumptions over 200 runs (full blue line); target consumption (dashed red line) and mean consumption associated with each tariff (pastel). Bottom: proportions p_t used over time for a single run.

Model 2



Results

With $\ell_{t,p} = \mathbb{E}[(Y_{t,p} - c_t)^2 | \text{past}]$ the regret $R_T = \sum_{t=1}^T \ell_{t,p_t} - \sum_{t=1}^T \min_{p \in \mathcal{P}} \ell_{t,p}$ is considered

Model 1

$$\ell_{t,p} = (\phi(x_t, p)^T \theta - c_t)^2 + p^T \Gamma p$$

For both models

- ▶ Estimate parameter θ with a Ridge regression $\hat{\theta}_{t-1} = \arg \min_{\hat{\theta}} \sum_{s=1}^{t-1} (Y_{s,p_s} - \phi(x_s, p_s)^T \hat{\theta})^2 + \lambda \|\hat{\theta}\|^2$ thus $\hat{\theta}_{t-1} = V_{t-1}^{-1} \sum_{s=1}^{t-1} Y_{s,p_s} \phi(x_s, p_s)$ with $V_{t-1} = \lambda I_d + \sum_{s=1}^{t-1} \phi(x_s, p_s) \phi(x_s, p_s)^T$
- ▶ Create a confidence set $\|\hat{\theta}_{t-1} - \theta\|_{V_{t-1}} \leq B_t$

Estimate Γ on the first n rounds

$$\hat{\Gamma}_n = \arg \min_{\Gamma} \sum_{t=1}^n (\hat{Z}_t^2 - p_t^T \hat{\Gamma} p_t)^2$$

with $\hat{Z}_t = Y_{t,p_t} - [\phi(x_t, p_t)^T \hat{\theta}_n]_C$

For p_1, \dots, p_n well chosen, $\|\hat{\Gamma}_n - \Gamma\|_{\infty} \leq \gamma_n$

- ▶ Estimate losses and get a confidence bound for each p thanks to B_t and γ_n

$$\tilde{\ell}_{t,p} = ([\phi(x_t, p)^T \hat{\theta}_{t-1}]_C - c_t)^2 + p^T \hat{\Gamma}_n p$$

and $\|\tilde{\ell}_{t,p} - \ell_{t,p}\| \leq \alpha_{t,p}$

- ▶ Select price level optimistically

$$p_t \in \arg \min_{p \in \mathcal{P}} \{\tilde{\ell}_{t,p} - \alpha_{t,p}\}$$

Theorem 1. For proper choices of confidence levels $\alpha_{t,p}, B_t, \gamma_n$, with $n = \sigma(T^{2/3})$ with probability at least $1 - \delta$ the regret is upper bounded as $R_T \lesssim T^{2/3} \ln^2 T / \delta \sqrt{\ln 1/\delta}$.

Model 2

$$\ell_{t,p} = (\phi(x_t, p)^T \theta - c_t)^2 + \sigma^2$$

Assumption. Attainability

$$\forall t \geq 1, \exists p_t^* \in \mathcal{P}, \phi(x_t, p_t^*)^T \theta = c_t$$

and thus $\min_{p \in \mathcal{P}} \ell_{t,p} = \ell_{t,p_t^*} = \sigma^2$

$$\tilde{\ell}_{t,p} = (\phi(x_t, p)^T \hat{\theta}_{t-1} - c_t)^2$$

and $\|\tilde{\ell}_{t,p} - \ell_{t,p}\| \leq \beta_{t,p}$

$$p_t \in \arg \min_{p \in \mathcal{P}} \{\tilde{\ell}_{t,p} - \beta_{t,p}\}$$

Theorem 2. For proper choices of confidence levels $\beta_{t,p}, B_t$ and regularisation λ , with probability at least $1 - \delta$ the regret is upper bounded as $R_T \lesssim \ln^2(T)$.

- ▶ Efficient algorithm: sub-linear regret
- ▶ Hard computation: non convex minimization problem

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